



Maciej Żurad

MACHINE LEARNING & COMPUTER VISION ENGINEER

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Experience

Machine Learning & Computer Vision Engineer

Belval, Luxembourg

LMO *May. 2023 - Present*

- Research and development of in-orbit servicing and space situational awareness (SSA)
- Leading ML training efforts; building tools and processes to automate and streamline experiments and model training pipelines

Lead Data Scientist & ML Engineer

Luxembourg

YOBA SA *Dec. 2018 - Apr. 2023*

- Data-driven optimization of business processes in retail lending
- Developing and deploying ML models for credit scoring
- Scraping public data sites to power corporate credit scoring engines
- Working on ML-based template-free invoice scanning
- Automating reporting and analysis tools
- Building tools for market research for corporate lending

Robotics Software Engineer

Luxembourg

AUTOMATION & ROBOTICS RESEARCH GROUP - INTERDISCIPLINARY CENTRE FOR SECURITY, RELIABILITY AND TRUST (SNT) *Feb. 2018 - Sep. 2018*

- Working on a proof-of-concept for autonomous airplane and bridge inspection using UAVs
- Development of robot process monitoring software (ROS, C++11)
- Development of sensor fusion components (ROS, C++11)
- Systems integration and administration using ROS and Linux

Research Assistant

Luxembourg

AUTOMATION & ROBOTICS RESEARCH GROUP - INTERDISCIPLINARY CENTRE FOR SECURITY, RELIABILITY AND TRUST (SNT) *Nov. 2015 - Jun. 2016 &*

- Qualified to finals of the 2016 DJI Developer Challenge
 - Development and configuration of robotics systems for UAVs in ROS using C++/Python
 - Preparing and running research experiments with UAVs
- Apr. 2017 - Nov. 2017*

Robotics Software Engineer

Luxembourg

AUTOMATION & ROBOTICS RESEARCH GROUP - INTERDISCIPLINARY CENTRE FOR SECURITY, RELIABILITY AND TRUST (SNT) *Feb. 2015 - Sep. 2015*

- Lead Programmer and System Integrator of CoRobots project for MUDAM robotics exhibition "Eppur Si Mouve"
- Programming behaviors for NAO humanoid robot in ROS using C++/Python
- Development of LED lighting for UAV using ARM microcontroller and node.js
- Development of software that orchestrates actions of a UAV and NAO robots using motion capture system
- OS administration of various Linux-based robotics systems (Gentoo, Ubuntu, BusyBox)

Research Assistant

Luxembourg

ICR RESEARCH GROUP, UNIVERSITY OF LUXEMBOURG *Jan. 2014 - Aug. 2014*

- Solved localization in ROS for NAO humanoid robots using fiducial markers
- Developed bindings from Prolog to C for fast matrix multiplications
- Prepared course material for a new university advanced robotics class

Software Engineer Intern

Poznan, Poland

SYGNITY S.A. *July 2012*

- Database migration from Excel to Oracle DB using Pentaho ETL software and JavaScript
- Development of XSLT forms in banking applications

Education

M.Sc. in Information and Computer Sciences

Luxembourg

UNIVERSITY OF LUXEMBOURG *Sep. 2015 - Feb. 2018*

- GPA: Excellent (18.5 / 20.0)
- Dual specialization: Artificial Intelligence and Information Security
- Master Thesis: *Deep Convolutional Neural Networks for Camera Relocalization* (Grade: 19.0/20.0)
- Intensive Study Programme in Information Security (ParIS project) in Lisbon, Portugal

Masters Exchange Student

NANYANG TECHNOLOGICAL UNIVERSITY (NTU)

- Studying Machine Learning, Computer Vision, Neural Networks, Fuzzy Systems and Embedded SW Dev

Singapore

Jul. 2016 - Dec. 2016

B.Sc.Eng in Computer Science

POZNAN UNIVERSITY OF TECHNOLOGY

- GPA: 4.43 / 5.0
- Member of Distributed Systems Group Student Club (2012 - 2013)
- Erasmus Exchange to University of Luxembourg (2013 - 2014)
- Diploma Thesis: *Design and implementation of communication protocols for self-organizing multi-hop ad hoc networks using XbeePRO-868 platform*

Poznan, Poland

Oct. 2011 - Feb. 2015

Awards

Finalist @ NASA Space Robotics Challenge

TEAM MOONRAIDERS

- ROS Lead and Machine Learning Specialist
- Created data generation pipeline for 6-DOF Pose Estimation task
- Developed and integrated pose estimation neural net with ROS

Remote

Jan - July 2021

Top Student Award @ uni.lu

SOPHIA UNIVERSITY

- Scholarship for Summer School in Asian Studies

Tokyo, Japan

July - Aug 2017

Winner @ LuxBlockHackathon

WINNING TEAM OF 750.000 XLM ~ 37.000 USD

- Development of a Decentralized Asset Management solution with Privacy and Know-Your-Customer regulations compliance on the Ethereum platform

Luxembourg, Luxembourg

8-9 May 2017

Open source projects

fincontracts

NODE.JS PACKAGES

- <https://doc.esdoc.org/github.com/asiron/fincontracts-lib>
- Interacting with FinContracts deployed on Ethereum blockchain
- Fully asynchronous code, based on async/await
- Example application using vorpal.js

robot_activity

ROS PACKAGE

- http://wiki.ros.org/robot_activity
- Controllable node lifecycle in ROS
- Automatically manages subscribers and services for you
- Allows for creation of super-nodes
- Dead simple API & integration with a supervisor

Publications

Target Tracking Optimization of UAV Swarms based on Dual-Pheromone Clustering

CYBERNETICS (CYBCONF), 2017 IEEE 3RD INTERNATIONAL CONFERENCE ON

- Maciej Zurad, Laurent Hentges, Leandro Gomes, Matthias Brust, Gregoire Danoy, Pascal Bouvry

Best Paper Award

21-23 June 2017

Towards an Autonomous Vision-Based Unmanned Aerial System against Wildlife Poachers

SENSORS 2015

- Miguel A. Olivares-Mendez, Changhong Fu, Philippe Ludivig, Tegawendé F. Bisseyandé, Somasundar Kannan, Maciej Zurad, Arun Annaiyan, Holger Voos and Pascual Campoy

Journal Publication

12 Dec. 2015

About me

General	Fast learner, Analytical mindset, Can-do attitude, Team player
CS Skills	Data Science, Machine Learning, Deep Learning, Robotics, Linux, Embedded, Mathematics
Programming Languages	Python (proficient), SQL (proficient), node.js (proficient), C/C++11 (proficient), JAVA (proficient)
ML Toolkits	tensorflow, keras, sklearn, pandas, numpy, scipy, matplotlib
Languages	English (proficient), Spanish (intermediate), Polish (native)
Sports & Hobbies	Cycling, Boulderling, Hiking, Electronics, Home Automation